
Phased Array Radar Basics

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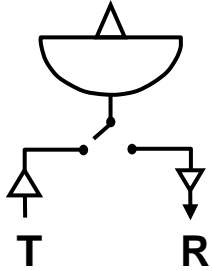
Outline

- ➔ ● **History and Evolution of Phased Arrays**
- **Phased Array Radar Fundamentals**
 - **Array Beamforming**
 - **Electronic Scanning**
 - **Active Transmit-Receive Modules**
- **Summary**



Radar Antenna Architectures

Dish Antenna



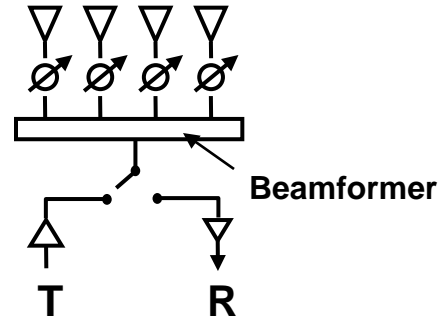
PRO
CON

- Very low cost
- Frequency diversity
- Slow scan rate
- High distribution loss
- Single point of failure



MILLSTONE

Passive Phased Array

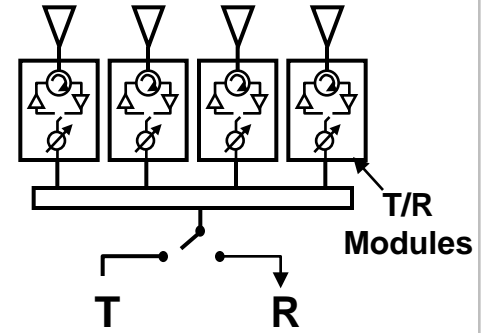


- Beam agility
- Effective radar resource management
- High distribution loss
- Higher cost



SPY-1

Active Phased Array



- Highest performance
- Effective radar resource management
- Low distribution loss
- Highest cost



THAAD



Dish Radar Example

- **MIT LL Millstone Radar**
 - 2 Klystrons with 3 MW peak power
 - 120 kW avg power
 - Center Frequency of 1295 MHz
 - 8 MHz bandwidth



- \$400,000/tube
- 7 ft x 1ft
- 600 lbs
- 3% duty cycle
- 42 dB gain

Millstone Klystron Tube

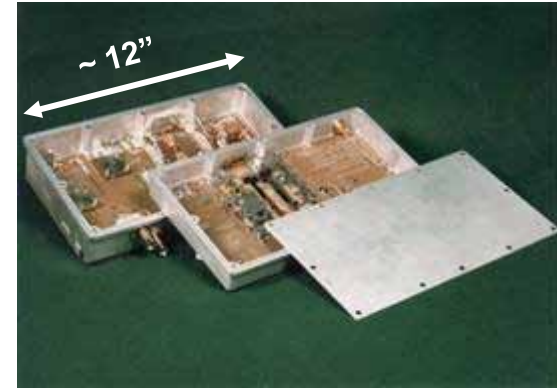
- **Advantages**
 - High output power
 - Low cost per watt
- **Disadvantages**
 - Single point of failure
 - Large size



Solid State Array Radar Example

- **PAVE PAWS**

- First all-solid-state array radar
- UHF Band
- 1800 active transceiver T/R modules, 340 W of peak power each



Transmit and Receive Modules

- **Advantages**

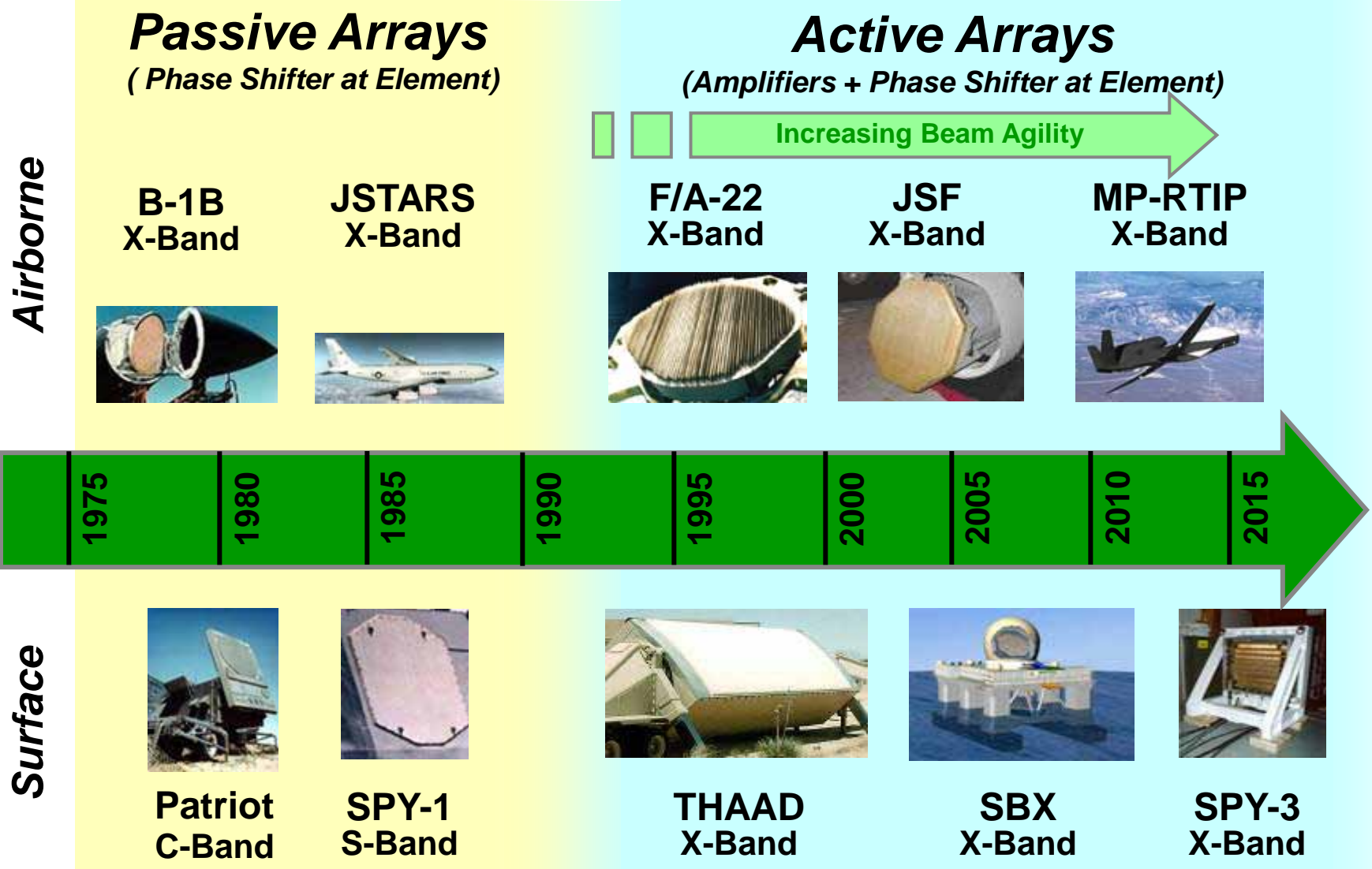
- Electronic beam agility
- Low maintenance (no moving parts)
- Graceful degradation

- **Disadvantages**

- Higher cost per watt



Phased Array Radar Evolution





Outline

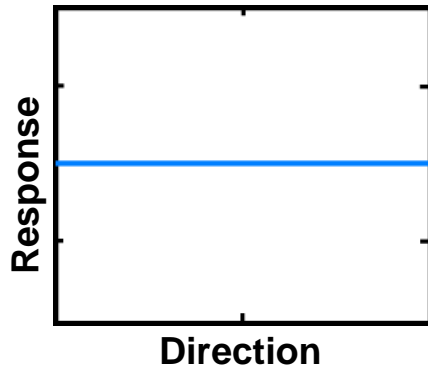
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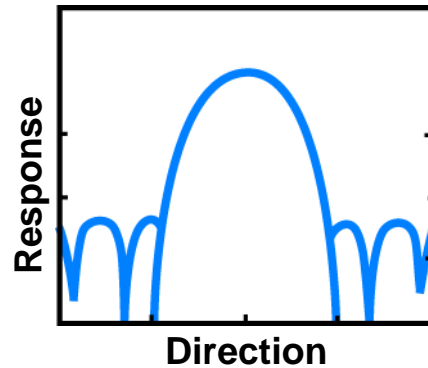
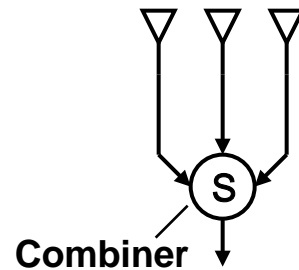
Array Beamforming

- Multiple antennas combined to enhance radiation and shape pattern

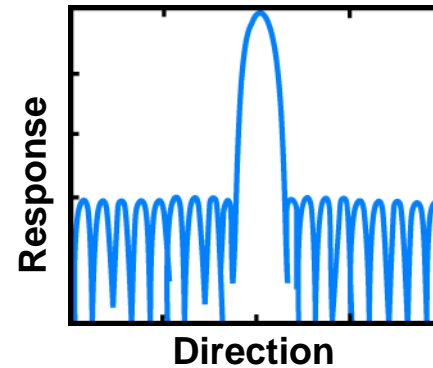
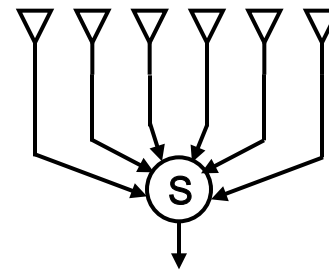
Isotropic Element



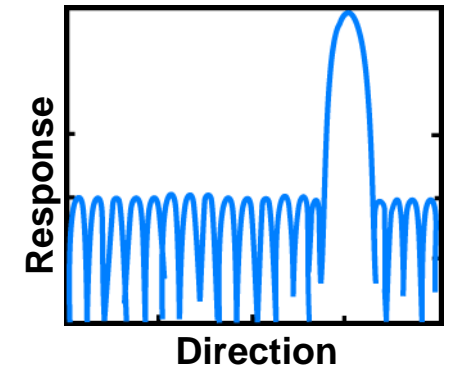
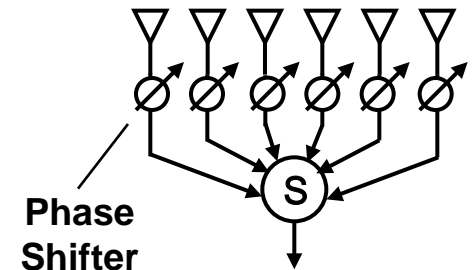
Array



Array



Phased Array

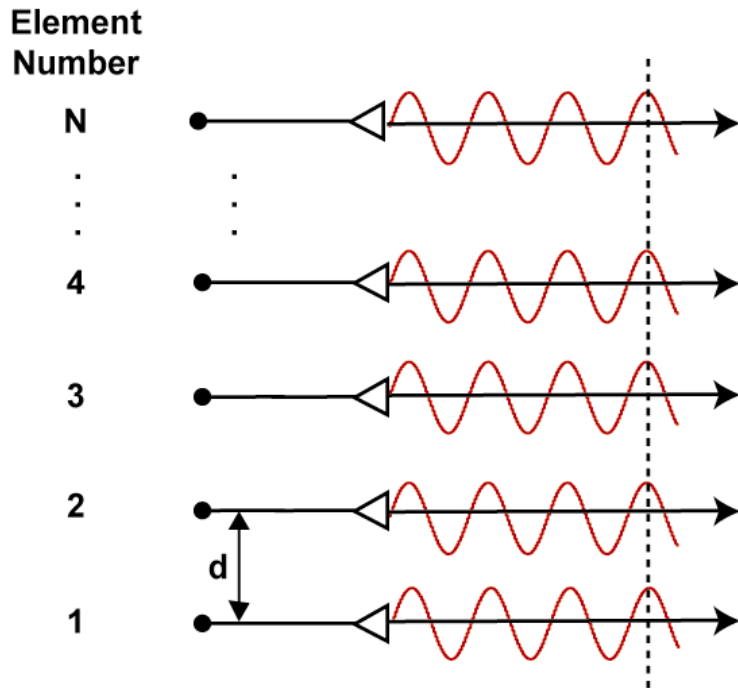




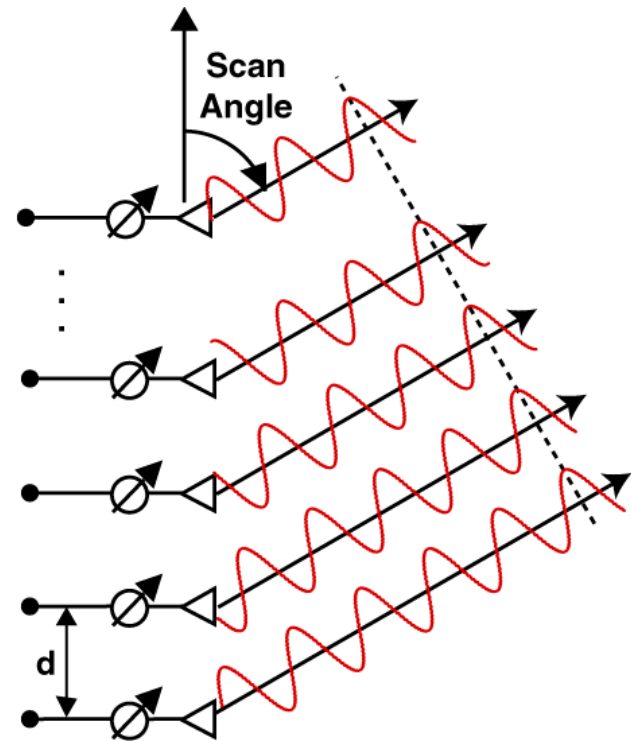
Array Beamforming (Beam Collimation)

- Want fields to interfere constructively (add) in desired directions, and interfere destructively (cancel) in the remaining space

Broadside Beam



Scan To 30 deg





Broadside Uniform Linear Array

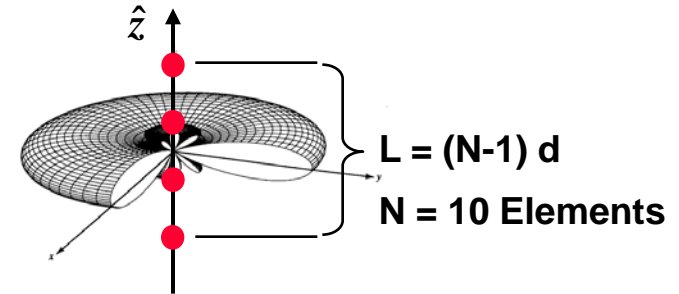
Design Goal

Maximum at $q = 90^\circ$

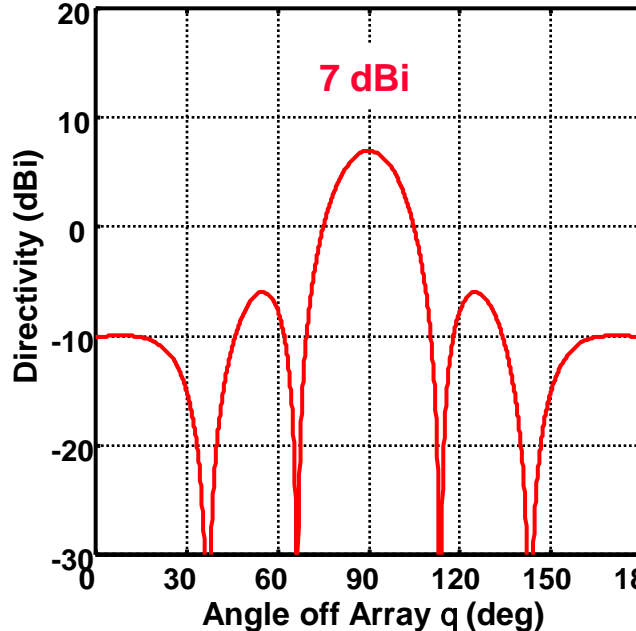
$$y = kd \cos q + b \Big|_{q=90^\circ} = 0$$

Required Phase

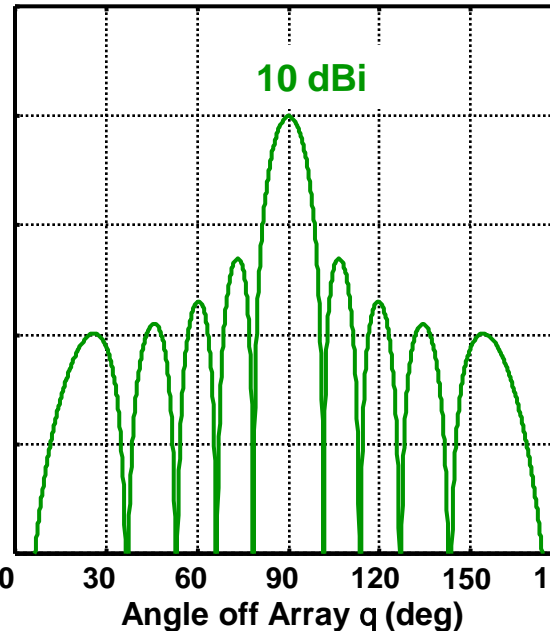
$$b = 0$$



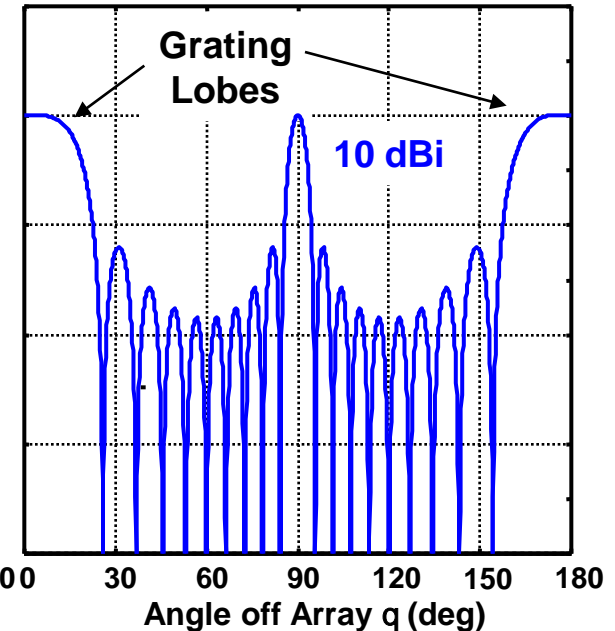
d = l / 4 separation



d = l / 2 separation



d = l separation

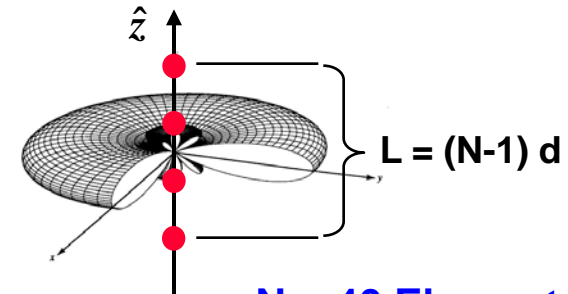


Limit element separation to $d < l$ to prevent grating lobes for broadside array



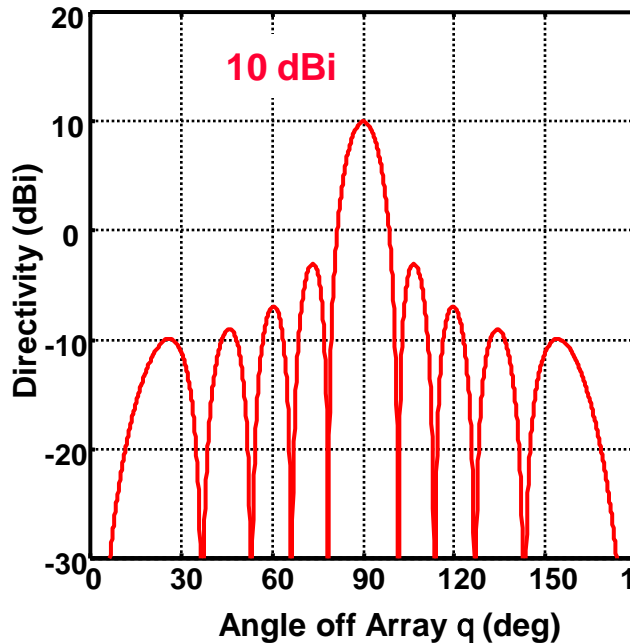
Increasing Broadside Linear Array Size by Adding Elements

- Element Separation $d = \lambda / 2$



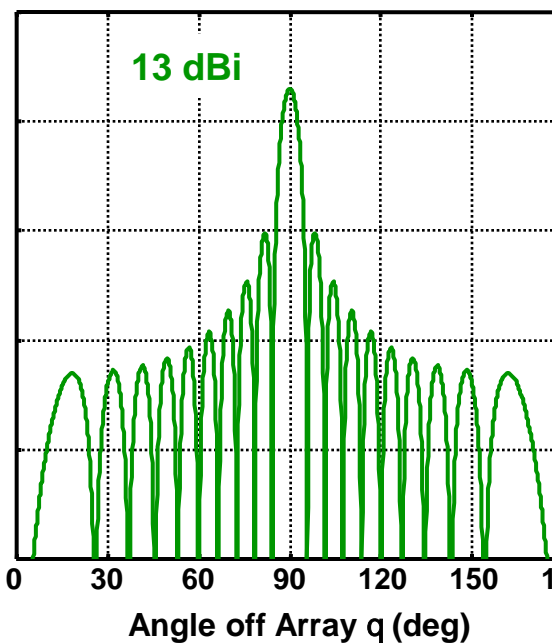
N = 10 Elements

10 dBi



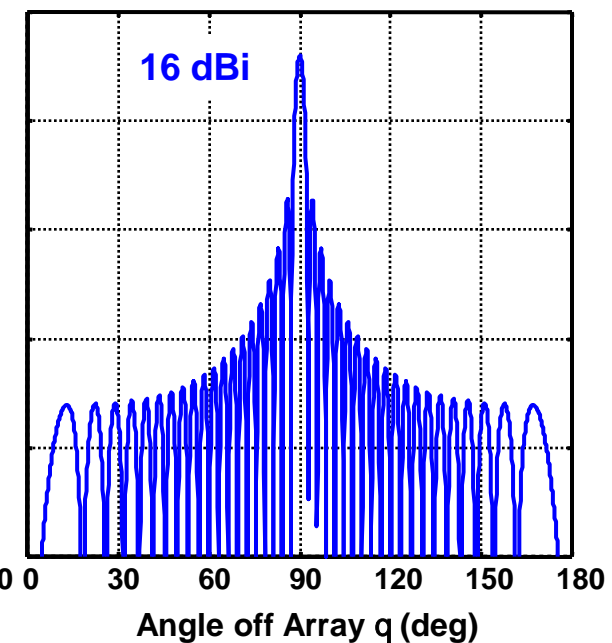
N = 20 Elements

13 dBi



N = 40 Elements

16 dBi



**Gain $\sim 2N(d / \lambda) \sim 2L / \lambda$
for long broadside array *without grating lobes****

* $d < \lambda$

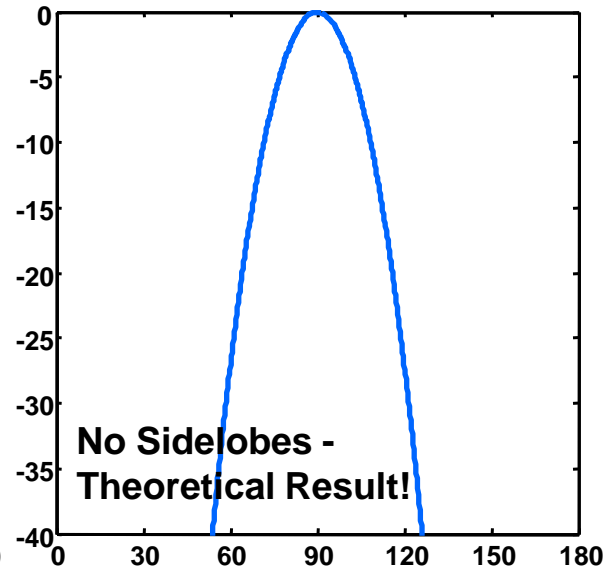
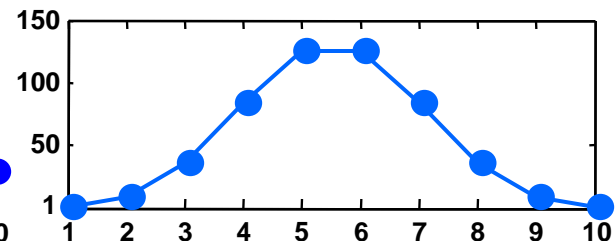
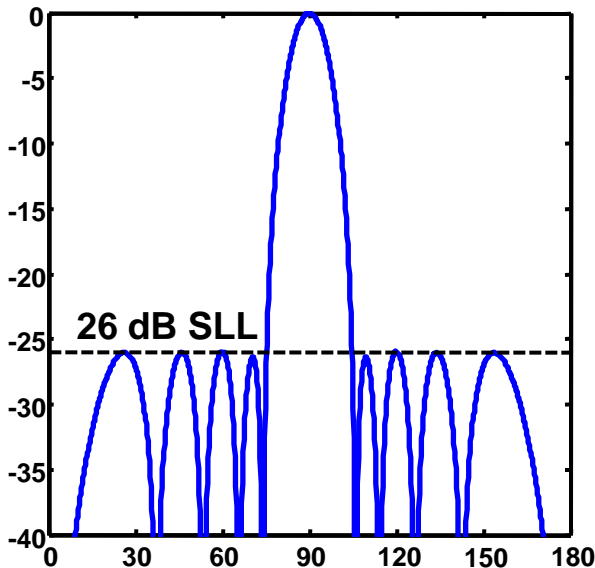
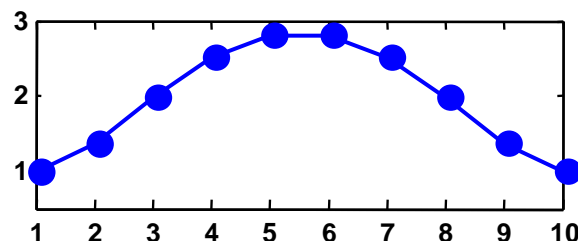
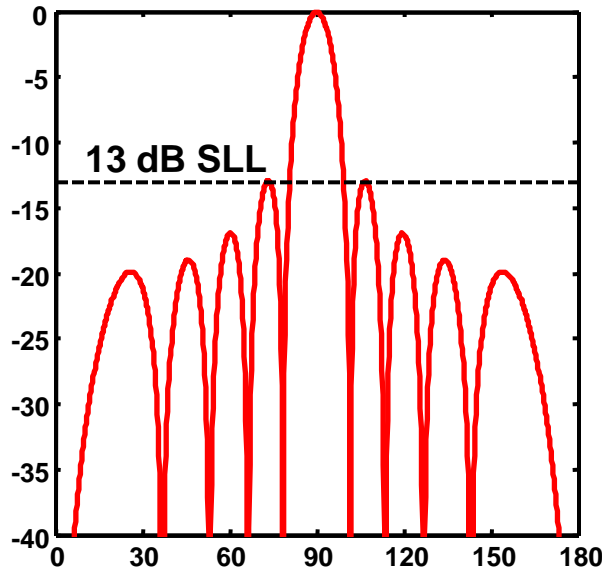
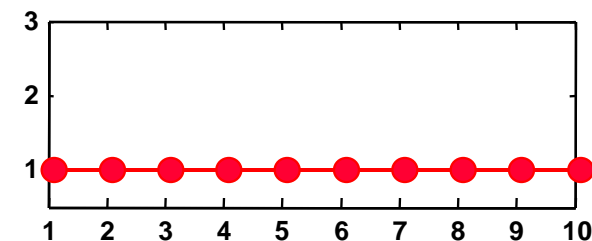


Excitation Amplitudes Tapers Across 10 Element Linear Array

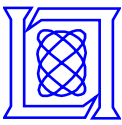
Uniform Amplitude

26 dB Dolph-Tschebyscheff

Binomial



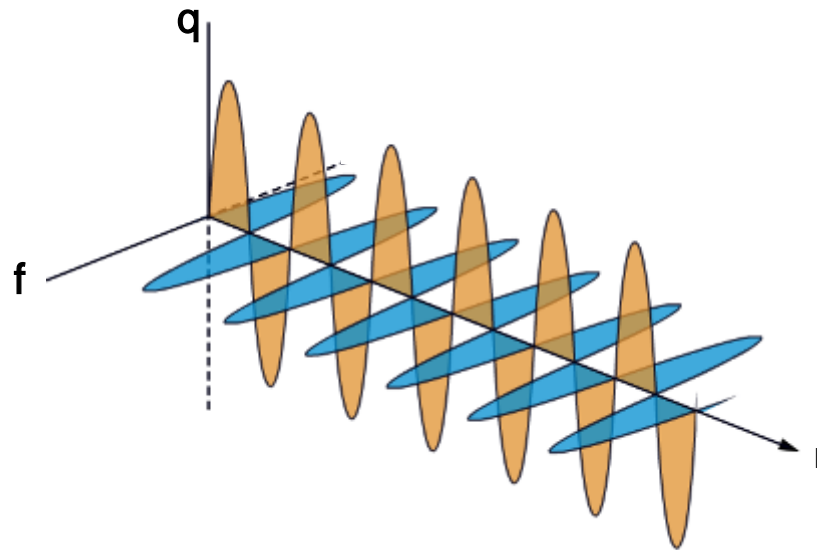
**Amplitude & Phase Errors Limit the Sidelobe Level (SLL)
That Can Be Achieved in Practice: > 40 dB is Challenging**



Polarization

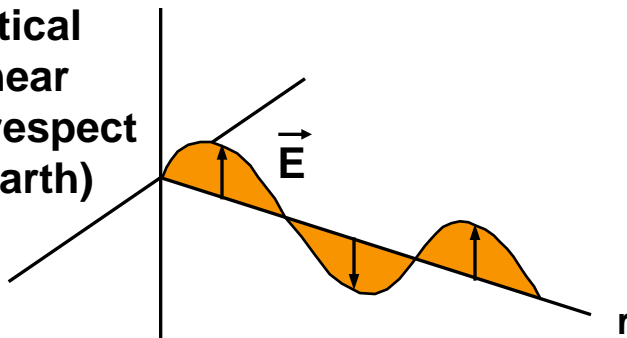
- Defined by behavior of the electric field vector as it propagates in time

Electromagnetic Wave

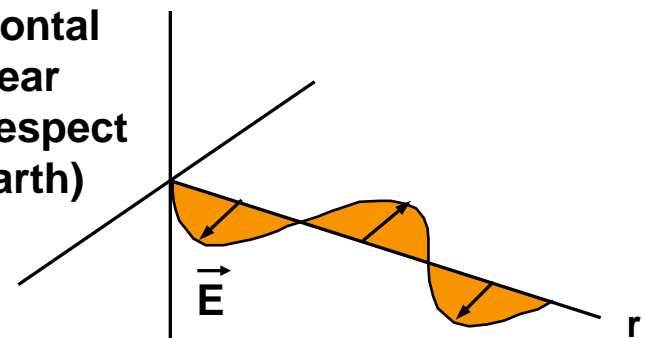


Electric Field
Magnetic Field

Vertical Linear
(with respect to Earth)

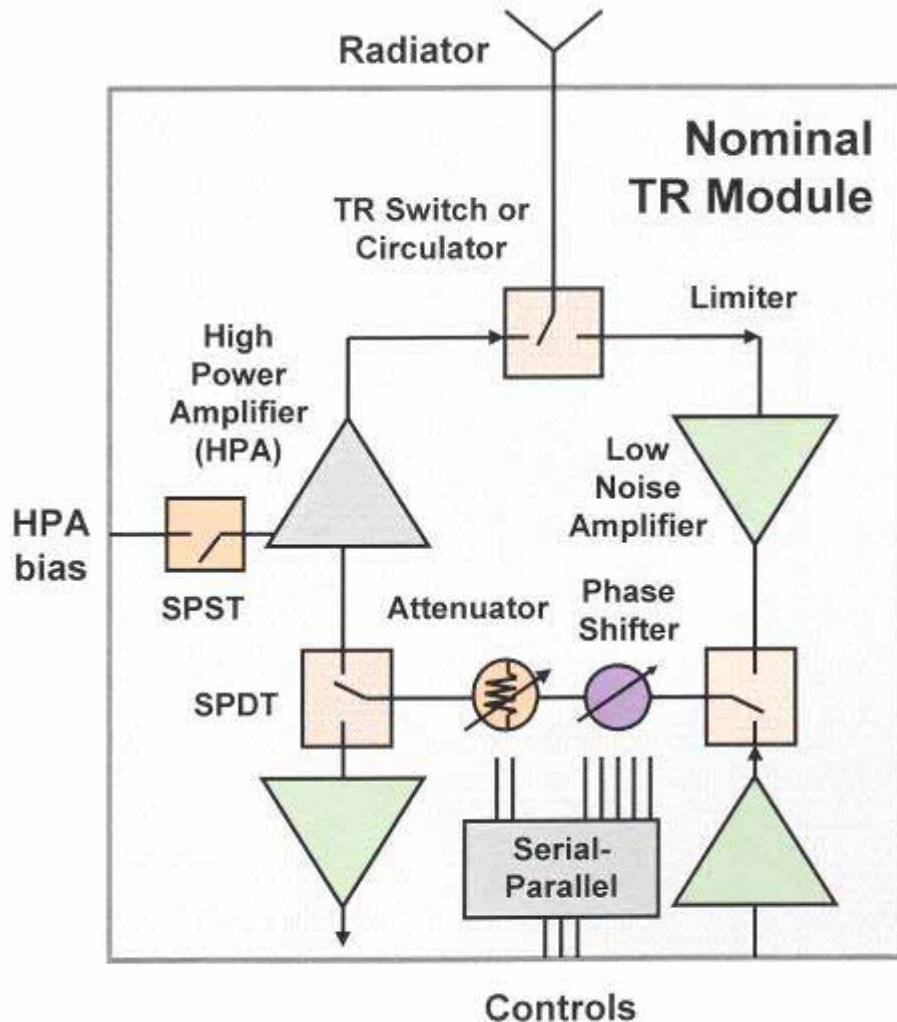


Horizontal Linear
(with respect to Earth)





Active Array T/R Module

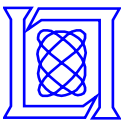


F-35 Radar

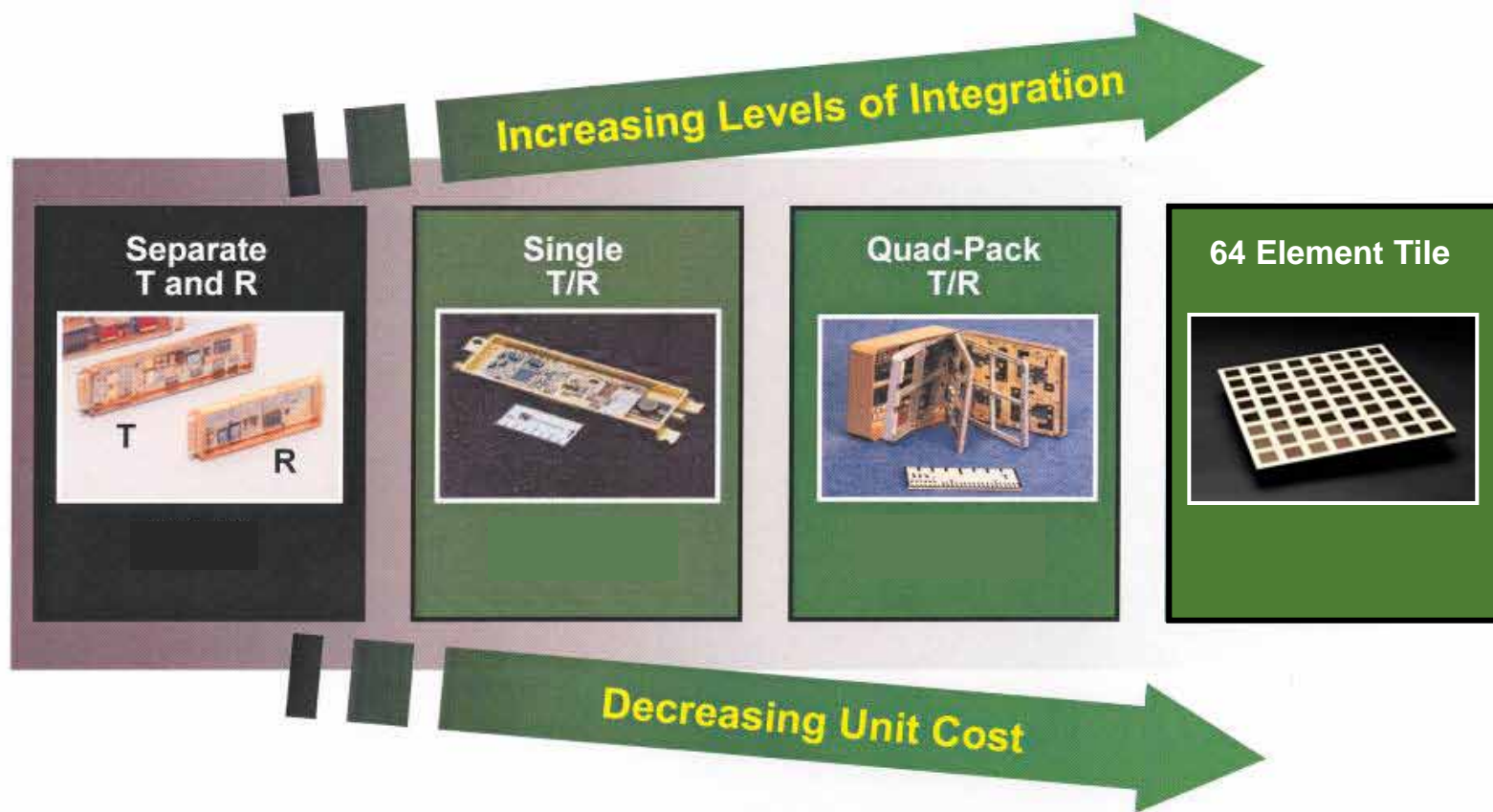


Critical Technologies:

- Power amplifiers
 - High gain
 - High efficiency
- Low noise amplifiers
 - Low signal intermodulation
 - Low drain power
- Packaging
 - Thermal management
 - Light weight



T/R Module / Subarray Integration



- High levels of integration reduce unit cost
- Automated assembly and test reduces touch labor cost



Summary

- **Phased array provides improvements in radar functionality and performance**
 - **Beam agility**
 - **Effective radar resource management**
 - **Graceful degradation with module failures**
- **Current trend is towards active arrays with distributed T/R modules**
 - **Large number of distributed active components and control**
 - **High levels of integration required to achieve low cost**



References

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